

Appendix

A common sampling technique often used in this setting is the Metropolis-Hastings algorithm, which is a Markov chain Monte Carlo (MCMC) method. The M-H acceptance probability for moving from state x to state x' is shown below, where each *state* is a DBN.

$$\alpha(x, x') = \min \left\{ 1, \frac{p(D|x')}{p(D|x)} \times \frac{p(x' \rightarrow x)}{p(x \rightarrow x')} \right\} = \min \left\{ 1, \underbrace{\frac{p(D|x')}{p(D|x)}}_{\text{likelihood ratio}} \times \underbrace{\frac{p(m')p(x|x', m')}{p(m)p(x'|x, m)}}_{\text{proposal ratio}} \right\}$$

where m is the move type that allows for a transition from state x to x' and m' is the reverse move type for a transition from state x' back to state x . The proposal ratio can be split into two terms: one is the ratio of the proposal probabilities for move types and the other is the ratio of selecting a particular state given the current state and the move type. The choice of scoring metric determines the likelihoods, and often $p(m')$ and $p(m)$ are chosen *a priori* to be simple to calculate or to actually cancel out.

Move type m	Proposal probability	$\frac{p(m')}{p(m)}$	$\frac{p(x x', m')}{p(x' x, m)}$
(M_1) add edge to G_1	P_a	$\frac{P_d}{P_a}$	$\frac{(E_1+1)^{-1}}{(P_{max}n-E_1)^{-1}} = \frac{P_{max}n-E_1}{E_1+1}$
(M_2) delete edge from G_1	P_d	$\frac{P_a}{P_d}$	$\frac{(P_{max}n-E_1+1)^{-1}}{E_1^{-1}} = \frac{E_1}{P_{max}n-E_1+1}$
(M_3) add edge to Δg_i	P_{ae}	$\frac{P_{de}}{P_{ae}}$	$\frac{m^{-1}(S_i+1)^{-1}}{m^{-1}(S_{max}-S_i)^{-1}} = \frac{S_{max}-S_i}{S_i+1}$
(M_4) delete edge from Δg_i	P_{de}	$\frac{P_{ae}}{P_{de}}$	$\frac{m^{-1}(S_{max}-S_i+1)^{-1}}{m^{-1}S_i^{-1}} = \frac{S_i}{S_{max}-S_i+1}$
(M_5) move edge from Δg_i to Δg_j	P_{me}	1	$\frac{(m(m-1))^{-1}(S_j+1)^{-1}}{(m(m-1))^{-1}S_i^{-1}} = \frac{S_i}{S_j+1}$
(M_6) locally shift t_i	P_{st}	1	$\frac{(2d+1)^{-1}}{(2d+1)^{-1}} = 1$
(M_7) merge Δg_i and Δg_{i+1}	P_m	$\frac{P_s}{P_m}$	$\frac{(m-1)^{-1}2^{(S_i+S_{i+1})^{-1}}(S_i+S_{i+1})^{-1}}{(m-1)^{-1}} = \frac{2}{(S_i+S_{i+1})\binom{S_i+S_{i+1}}{S_i}}$
(M_8) split Δg_i	P_s	$\frac{P_m}{P_s}$	$\frac{(m-1)^{-1}}{(m-1)^{-1}(S_i/2)^{-1}\binom{S_i}{x}^{-1}} = (S_i/2)\binom{S_i}{x}$
(M_9) create new Δg_i	P_{ag}	$\frac{P_{dg}}{P_{ag}}$	$\frac{(m+1)^{-1}}{(N-m)^{-1}n^{-2}} = \frac{(N-m)n^2}{m+1}$
(M_{10}) delete Δg_i	P_{dg}	$\frac{P_{ag}}{P_{dg}}$	$\frac{(N-m-1)^{-1}n^{-2}}{m^{-1}} = \frac{m}{(N-m-1)n^2}$

KNKT

KNUT

UNUT

Table 1: E_1 is the total number of edges in G_1 , S_{max} is the maximum number of transitions allowed in a single transition time, P_{max} is the maximum parent set size, and S_i is the number of edge changes in the set Δg_i . The proposal ratio is the product of the last two columns. The KNKT setting uses moves $(M_1) - (M_5)$, KNUT uses moves $(M_1) - (M_6)$, and UNUT uses moves $(M_1) - (M_{10})$, in each case with the proposal probabilities appropriately normalized to add to 1.

All of the F1-measures for the nsDBNs learned under the UNUT setting are shown in Table 2 below.

A		λ_e				
		1.0	2.0	3.0	4.0	5.0
λ_m	1.0	0.434	0.942	0.947	0.974	0.992
	2.0	0.676	0.956	0.955	0.991	0.991
	5.0	0.921	0.955	0.973	0.973	0.991
	10.0	0.926	0.955	0.966	0.983	0.979
	50.0	0.880	0.881	0.904	0.892	0.881

B		λ_e		
		2.0	3.0	5.0
λ_m	1.0	0.949	0.951	0.947
	2.0	0.938	0.952	0.936
	5.0	0.953	0.946	0.940

Table 2: F1-measure for different values of λ_e and λ_m under the UNUT setting. F1-measures over 0.9 are shaded in light gray and the best score is shown in bold. **A**: F1-measures for the nine variable dataset defined by the nsDBN in Figure 1A. **B**: F1-measures for the large 100 variable dataset.