

Approximate Algorithms

If we cannot find an **optimal** solution to an optimization problem, we might be able to **approximate** it.

Definition 1. *An approximate algorithm has a **ratio bound** $\rho(n)$, if for any input of size n , the optimal solution $C^*(n)$ and the algorithm solution $C(n)$ satisfy the relation:*

$$MAX \left[\frac{C(n)}{C^*(n)}, \frac{C^*(n)}{C(n)} \right] \leq \rho(n).$$

Vertex Cover

Given a graph $G = (V, E)$, a **vertex cover** of G is a set of vertices $V' \subseteq V$ such that each edge in E is adjacent to at least one vertex in V' .

The **vertex cover optimization problem** is to find a vertex cover of minimum size.

The problem is \mathcal{NP} -complete.

Approximation Algorithm

Approximate-Vertex-Cover(G)

1. $C \leftarrow \emptyset$
2. $E' \leftarrow E$
3. While $E' \neq \emptyset$ do
 - 3.1 Choose an arbitrary edge (u, v) in E'
 - 3.2 $C \leftarrow \{u, v\}$
 - 3.3 remove from E' every edge adjacent to u or v
4. return C

Analysis

Theorem 1. *The algorithm returns a vertex cover, and has a ratio bound of 2.*

Proof.

C is a vertex cover since the algorithm terminates when $E' = \emptyset$.

Let A be the set of edges chosen in line 3.1.

No two edges in A have a common vertex, thus any optimal vertex cover C^* satisfied

$$|C^*| > |A|$$

but $|C| = 2|A|$ thus,

$$\frac{|C|}{|C^*|} \leq 2$$

□

Traveling Salesman Problem

Given a complete graph $G = (V, E)$ with costs $c(u, v)$ on the edges, find a Hamiltonian cycle of minimum cost.

We approximate this problem in the case where the cost function $c()$ satisfied the **triangular inequality**: for all u, v and w ,

$$c(u, w) \leq c(u, v) + c(v, w).$$

Approximate-TSP(G,c)

1. Compute a minimum spanning tree T of G .
2. Compute an Euler cycle of T starting at an arbitrary vertex a .
3. Compute the TSP by starting at vertex a , following the Euler path, skipping vertices that were already visited.

Analysis

Theorem 2. *The algorithm returns an Hamiltonian path of G , with approximate ratio bound of 2 on the total cost.*

Proof. Let H be the path computed by the algorithm, H^* an optimal path.

For a set of edges X , let $c(X) = \sum_{e \in X} c(e)$.

Since removing an edge from H^* gives a spanning tree

$$c(T) \leq c(H^*).$$

Let W be the Euler tour on T , it visits every edge twice, thus

$$c(W) = 2c(T) \leq 2c(H^*).$$

If W is not an Hamiltonian cycle, we remove vertices from W to get an Hamiltonian cycle.

Assume that W includes the segment $\dots vuw \dots$ and u already appears on the path.

We remove u and connect v directly to w , but

$$c(v, w) \leq c(v, u) + c(u, w)$$

so we don't increase the path cost.

Thus,

$$c(H) \leq c(W) = 2c(T) \leq 2c(H^*).$$

□

Theorem 3. *The TSP problem with a cost function that satisfies the triangular inequality is NP-complete.*

Limits on Approximation

Theorem 4. *If $P \neq NP$ then there is no polynomial time approximation algorithm for the general TSP problem for any $\rho \geq 1$.*

Proof.

Assume that we have such an approximation algorithm, we'll use it to solve the Hamiltonian problem.

Given a graph $G = (V, E)$, let G' be a complete graph with cost function

$$c(u, v) = \begin{cases} 1 & \text{if } (u, v) \in E \\ \rho|V| + 1 & \text{otherwise} \end{cases}$$

If G has an Hamiltonian cycle, then G' has a TSP of cost $|V|$ (that cycle).

Any TSP solution in G' that is not an Hamiltonian cycle in G has cost at least

$$\rho|V| + 1 + |V| - 1 > \rho|V|.$$

Assume that we run an approximation algorithm AP with ratio bound ρ on G' :

If G has an Hamiltonian path, AP will return that path.

If G does not have an Hamiltonian path, AP will return a TSP with cost more than $\rho|V|$.

Thus, AP solves the Hamiltonian path problem in G . \square

Fully Polynomial-Time Approximation

The **error bound** of an approximation scheme is ϵ
iff

$$\frac{|C - C^*|}{C^*} \leq \epsilon$$

A problem has a **fully polynomial-time approximation** scheme if for any $\epsilon > 0$ there is an algorithm for the problem with an ϵ ratio bound that is polynomial in both the problem size n and $1/\epsilon$.

The Subset-Sum Problem

The **subset-sum** decision problem: Given a set $S = \{x_1, \dots, x_n\}$ of positive integers and an integer t , is there a subset of S that sums to t .

The subset-sum decision problem is \mathcal{NP} -complete.

The **subset-sum** optimization problem: Given a set $S = \{x_1, \dots, x_n\}$ of positive integers and an integer t , find a subset of S with the largest sum less than t .

Exponential Algorithm

1. For $i = 0$ to n do
 - 1.1 Compute all the sums bounded by t from subsets of up to i elements of S .

Each iteration is polynomial in the number of sums in the previous iteration.

This algorithm is exponential since the number of different sums can grow exponentially in n .

Approximation Algorithm

1. For $i = 0$ to n do
 - 1.1 Compute all the sums bounded by t from subsets of up to i elements of S .
 - 1.2 Remove sums that are within $(1 - \epsilon/n)$ factor of other sums.

Run-Time

Let L_i be the collection of sums after the i -th iteration.

If $z, z' \in L_i$, then $z' > z(1 - \frac{\epsilon}{n})$, and all the elements are smaller than t .

Thus, there could be no more than k elements where

$$t(1 - \frac{\epsilon}{n})^k < 1$$

or

$$k = \frac{\log t}{-\log(1 - \epsilon/n)} \leq \frac{n \log t}{\epsilon}$$

Thus, the run-time is polynomial in n and $1/\epsilon$.

How good is the approximation?

Let y be the optimal solution and z the approximate one.

Since we only removed elements from the list $z \leq y$.

Since whenever we removed an element there was another element in the list that was within $1 - \epsilon/n$ of the removed element

$$y\left(1 - \frac{\epsilon}{n}\right)^n \leq z.$$

Thus,

$$(1 - \epsilon)y \leq z \leq y$$